

EFFINO

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The program EFFINO (Environment For Fitting Nuclear Optics) evaluates Mössbauer absorption and time spectra both in nuclear forward scattering and in grazing incidence reflection geometry. Time-integral prompt and delayed angular scan spectra are also treated. The time spectra are calculated by Fourier transformation from frequency to time domain. The electric quadrupole and magnetic dipole fields at the nuclear sites are considered static at present. The specimen in both forward scattering and grazing incidence is assumed to be a multilayer, with individual thickness and interface roughness (the latter only for the grazing incidence case at present) and electronic index of refraction. Up to eight different layers plus eight repetition periods of those layers are treated. Each layer may contain zero to eight nuclear sites (zero in all layers being prompt X-ray reflectivity), with their own effective thickness or (for grazing incidence) their own complex nuclear index of refraction. From the forward scattering amplitude, a differential 4×4 propagation matrix is constructed for each layer. Several experimental spectra of the same or different type(s) can be fitted simultaneously. Correlations between parameters of the same or of different spectra can be introduced.

Keywords: nuclear optics, correlations, energy domain, time domain, forward scattering, grazing incidence, inequivalent nuclear site, cover layer, substrate layer, periodic multilayer, simultaneous fit

1. Introduction

The theory of the Mössbauer absorption of γ radiation in the forward scattering geometry was described by Blume and Kistner [1] and successfully applied for the calculation of absorption spectra of single crystals [2] as well as for powder samples polarized in external magnetic fields [3]. They used a complex 2×2 index of refraction matrix n , corresponding to the two independent states of polarization. n was expressed by the coherent forward scattering amplitude f . Grazing incidence Mössbauer spectra were calculated by Andreeva et al. in several papers [4–8]. They started from the nuclear current density expression of the susceptibility tensor χ given by Afanas'ev and Kagan [9] and used the covariant formalism of anisotropic optics introduced by Federov [10] and applied for stratified media by Borzdov et al. [11]. Deák et al. clarified the conditions under which the nuclear susceptibility tensor can be expressed in terms of the forward scattering amplitude and brought Andreeva's results

into a closed reflectivity formula [12]. As recently shown [13], the general description of specular reflection of grazing incidence Mössbauer radiation by the dynamical theory of Mössbauer optics of Hannon and Trammell [14,15] leads, after a unitary transformation, to the same 4×4 differential propagation matrix M as that of Deák et al. [12]. The calculation of the amplitudes of the reflected radiation in the energy domain has been reduced to the 2×2 block-matrix exponential expression such that the analytical solutions of Blume and Kistner could be used for time-effective numerical calculations [12]. Such mathematical expressions are implemented in the EFFINO code.

The program EFFI [16] has developed over the years in several steps from the Mössbauer fit program MOSFUN [17] which already used [3] the formalism of Blume and Kistner for the calculation of Mössbauer absorption spectra. The main concern was to enable handling and fitting several data sets simultaneously whereby each data set (not necessarily a Mössbauer spectrum) may have its own “theory”, so that the program becomes an “environment” for parameter fitting. EFFINO (= Environment For Fitting Nuclear Optics) is the implementation of EFFI for fitting energy-domain and time-domain resonant nuclear (and electronic) scattering spectra in the two Nuclear Optical limits, i.e., in the forward scattering and in the grazing incidence geometry.¹

The spectrum parameters in EFFINO are determined by least squares fitting (Newton or gradient). Up to 16 spectra can be evaluated simultaneously. The matrix used for (linearly) correlating parameters and variables of a fit as first introduced by Kulcsár et al. [18] has been generalized to products of parameters and can now be more flexibly used. The physical theories and the main part of organization are in Fortran 77 code whereas the X-window subroutines are written in C-code [19]. The program was developed on PCs running the LINUX system and is available from [16].

2. Theoretical aspects

Both in the forward direction and in scattering geometry the sample is considered to consist of layers. Each layer is described by three parameters, the thickness and the real and imaginary part of the scalar electronic susceptibility χ at the nuclear transition energy. A layer may contain 0–8 inequivalent nuclear sites (zero in all layers being the prompt X-ray reflectivity case). If the hyperfine fields of sites are related to each other by symmetry operations (equivalent sites) an n -fold rotation axis normal to the layer, a twofold axis in the layer and the time inversion operator are provided for calculating the forward scattering amplitudes of the set of equivalent sites. (The time inversion operator is useful for magnetically ordered structures or samples in applied magnetic fields where the energy spectrum of the nuclear states at different sites is the

¹ In another implementation of EFFINO fitting of spin-polarized neutron reflectivity data of anisotropic (magnetic) multilayers is provided in a very similar scheme, making use of the transformation between the anisotropic optics of γ -rays and neutrons, respectively, as described in [23].

same but the polarization of the states differs due to opposite hyperfine magnetic field directions.)

The minimum number of layers is 1 for synchrotron radiation and 2 for energy domain Mössbauer measurements, the first layer in the latter case representing a thin Mössbauer source (not taking self-absorption into account). In grazing incidence scattering geometry, a single cover layer, n different “sandwich” layers and a substrate layer are considered. A number of (or all) sandwich layers may repeat n_{repeat} times (periodic multilayer case). Typically the cover and substrate layers do not contain nuclear scatterers, but the program treats all types of layers in the same way, except for the repetition period of the sandwich layers.

The Hamiltonian describing the physics at each site is the nuclear spin Hamiltonian of the nuclear ground and excited states with half integer spin (even spins have not been implemented yet) and a (presently) static magnetic dipole, electric monopole, and quadrupole field at the nucleus. Only magnetic dipole radiation is implemented at present.

In addition to the internal hyperfine field at the nuclei, an external magnetic field can be defined which is simply added to the internal fields. For conventional Mössbauer absorption, the external field at the source is independent of the field at the absorber.

The basic equation of the dynamical theory [20] describing scattering by a stratified specimen in the grazing incidence limit is eq. (A3) of [20]. With the following notation, $g_0 = k \sin \theta$ the component of the wave vector k normal to the surface, θ the angle of grazing incidence in the vacuum, $G = 4\pi N f / (2k \sin \theta)$, N the density of the scattering centers and f the 2×2 coherent forward scattering amplitude. The differential propagation [11,12] (or scattering [20,21]) matrix of layer l is given by a 4×4 complex matrix

$$M_l = \begin{pmatrix} I \sin \theta + \frac{\chi_l}{2 \sin \theta} & \frac{\chi_l}{2 \sin \theta} \\ -\frac{\chi_l}{2 \sin \theta} & -I \sin \theta - \frac{\chi_l}{2 \sin \theta} \end{pmatrix}, \quad (2.1)$$

where the complex susceptibility tensor $\chi_l = (4\pi N_l / k^2) f_l$ and the 2×2 unity matrix I were introduced.

Solely for computational efficiency reasons, we now apply to eq. (2.1) a unitary transformation $M'_l = C M_l C^{-1}$ with

$$C = \frac{1}{\sqrt{2}} \begin{pmatrix} I & -I \\ I & I \end{pmatrix} \quad (2.2)$$

to get the differential propagation matrix in the form

$$M'_l = \begin{pmatrix} 0 & I \sin \theta + \frac{\chi_l}{\sin \theta} \\ I \sin \theta & 0 \end{pmatrix} \quad (2.3)$$

from which for homogeneous thin layers l of thickness d_l the characteristic matrix $L_l = \exp(ikd_l M_l')$ can be calculated in closed form:

$$L_l = \begin{pmatrix} \cosh(F_l) & \frac{1}{x_l} F_l \sinh(F_l) \\ x_l F_l^{-1} \sinh(F_l) & \cosh(F_l) \end{pmatrix}, \quad (2.4)$$

where $F_l = kd_l \sqrt{-I \sin^2 \theta - \chi_l}$ and $x_l = ikd_l \sin \theta$ [12]. For multilayers the total characteristic matrix is simply the matrix product of the layer characteristic matrices L_l , i.e., with $L = L_N \cdots L_2 L_1$ the reflectivity matrix reads

$$r = (L_{[11]} - L_{[12]} - L_{[21]} + L_{[22]})^{-1} (L_{[11]} + L_{[12]} - L_{[21]} - L_{[22]}), \quad (2.5)$$

where $L_{[ij]}$ ($i, j = 1, 2$) are the 2×2 submatrices of the total characteristic matrix L [12].

To calculate L in eq. (2.4), we first have to calculate the 2×2 square root matrix F . This can be done by using the identity

$$G^{1/2} = \frac{G + I\sqrt{\det \bar{G}}}{\sqrt{\text{Tr } G + 2\sqrt{\det \bar{G}}}}, \quad (2.6)$$

where G is 2×2 matrix. The sinh and cosh functions are calculated from their exp forms. The exponential of the 2×2 matrix G can be expressed by the scalar invariants of G [1], hence

$$\exp G = \exp\left(\frac{1}{2} \text{Tr } G\right) \left[\cos \sqrt{\det \bar{G}} I + \frac{\sin \sqrt{\det \bar{G}}}{\sqrt{\det \bar{G}}} \bar{G} \right], \quad (2.7)$$

where $\bar{G} = G - \frac{1}{2} I \text{Tr } G$.

To calculate the characteristic matrix of a substrate layer, we have to find the limit of L for $d \rightarrow \infty$. From eqs. (2.5) and (2.7), the corresponding limit is given by

$$L^\infty = \begin{pmatrix} I & s\left(\sqrt{I + \frac{\chi}{\sin^2 \theta}}\right) \\ s\left(\sqrt{I + \frac{\chi}{\sin^2 \theta}}\right)^{-1} & I \end{pmatrix}, \quad (2.8)$$

where $s = \text{sgn}[\text{Re}(\text{Tr } F)]$ is the sign of the real part of the trace of F .

This algebra turns out to be numerically very stable. In a single precision implementation of the optics routine the product up to 16 matrices (corresponding to 16 *different* layers) can be handled without serious numerical instabilities. In double precision the number of layers also doubles. The double precision algorithm for a 1024 channel spectrum needs 0.92 s calculation time on a 166 MHz Pentium computer with 512 K cache and 32 Mbyte RAM. The majority (80%) of the time is taken up by the optics routine.

For grazing incidence, the reflectivity matrix is calculated as a function of two variables (vs. time and angle and vs. velocity and angle), for time domain and energy

domain spectra, respectively. By adding the corresponding time or energy channels, an option is provided for fitting time-integral or energy-integral reflectivity curves (angular scans). In this routine, in the event of no defined resonant scatterers in the multilayer, the hyperfine algorithm is skipped in which special case the electronic scattering, i.e., the non-resonant X-ray reflectivity curve, is fitted.

Each layer has its own interface roughness which is treated in a rather general way, using a characteristic matrix technique (similar to the treatment of the layer structure) allowing for roughness at interfaces of anisotropic layers [22].

3. Program description

The structure of EFFINO is designed to accomplish a simultaneous fit of theoretical curves to data sets of different type requiring different physical model functions (“theories”) like synchrotron scattering spectra and Mössbauer absorption spectra. Moreover, to each nuclear site an adequate theory is attached so that one site may have static hyperfine fields and another fluctuating fields (relaxation theory not yet implemented).

Simultaneous fitting requires the restriction of parameters to those common to different subsets of theories. This essential feature of EFFINO is implemented by a matrix called “transformation matrix” in the Mössbauer program SIRIUS [18] or “correlation matrix” in MOSFUN [17]. The first notation will be used here. The transformation matrix T maps the parameters p_i , $i = 1, \dots, n$, to be fitted to the variables v_k , $k = 1, \dots, \nu$, defined by the theories $v_k = \sum_i^n T_{ki} p_i$. If T is diagonal ($n = \nu$) there are no correlations and the number of parameters is equal to the number of variables. For a large number of variables the matrix T becomes tortuous. Therefore small subsets of variables are selected with their own transformation matrix T^τ :

$$v_k^\tau = \sum_i^{n^\tau} T_{ki}^\tau p_i^\tau. \quad (3.1)$$

EFFINO allows for free handling of the matrices, in order to combine and split subsets and the corresponding matrices (τ is free), and to rearrange parameters and/or variables inside subsets. In addition new parameters p_j^τ may be defined which are products of the original parameters: $p_l^\tau = p_i^\tau p_j^\tau$ such that the number of columns n^τ is larger than the number of rows ν^τ (number of variables) of the matrix. These products make it possible to fit (or to fix) ratios of parameters, which is often desired for intensity parameters of subspectra or between spectra.

Parameters are generally allowed to be fitted and they belong to a transformation matrix, whereas constants are listed and handled separately. As an example, the variables and constants of the grazing incidence time spectrum of a layer structure are listed and described in this section.

The default values of the matrices T^τ are unity matrices such that the parameters of the theory are the fit variables. The structure of the theory is such that several

Table 1
Variables of the theory for grazing incidence time spectrum. Angles of global variables are defined with respect to the laboratory coordinate system.

Level	Variable	Comment
GLOBAL	<i>counts</i>	total number of counts
	<i>background</i>	average number of background counts
	<i>t_shift</i>	zero-time shift
	<i>P_xsi, P_eta, P_zeta</i>	Poincaré vector of the synchrotron beam
	<i>Hext</i>	external magnetic field
LAYER	<i>phi, theta, psi</i>	orientation of the scatterer
	<i>thicklay</i>	thickness of the layer
	<i>r_chilay, i_chilay</i>	electronic susceptibility of the layer
	<i>roughness</i>	in units of <i>thickness</i>
SITE	<i>thickness</i>	effective thickness of nuclear scatterers
	<i>G_width, L_width</i>	Gaussian and/or Lorentzian broadening
	<i>is_shift</i>	isomer shift
	<i>Hi</i>	hyperfine magnetic field defined in the principal axes system of the EFG
	$\pm EFG, eta$	Quadrupole splitting and asymmetry parameter of the EFG with the sign of V_{zz}
		orientation of the EFG defined in the principal axes system of the scatterer

levels can be defined. There are global variables and constants which do not depend on the nuclear site or the individual layers. For some quantities, the user has the choice of defining them as constants or as parameters. Typical such quantities are the Poincaré vector ($P_{xsi}, P_{eta}, P_{zeta}$) of the synchrotron beam, the time-zero shift t_{shift} , the external magnetic field, the Eulerian angles $phi, theta, psi$ of the orientation of the specimen in the laboratory system, etc. These values are often known from external measurements but can be included in the list of fit parameters.

EFFINO, like MOSFUN, is command-driven. An EFFINO command consists of two letters and optional command line inputs (e.g., RD $\{file.dat\}$ = “read data from $file.dat$ ”). There belongs a command/option buffer to each command. Up to 6 buffers are handled. Command/option buffers can be created at any time during the fit session. They should at least contain one command to be executed and can be recursively called. An empty command “CD” executes the content of the default (first) buffer $b1$; CD $b3$, for example, executes the command string in $b3$, etc. EFFINO commands can be concatenated by a double ampersand “&&”: CD $\{option\}$ && CD' $\{option'\}$, etc. An option may consist of concatenated commands and be stored in a buffer, so that a long chain of commands can be constructed in order to avoid excessive typing during fitting sessions.

A set of parameters can be excluded from variation during fitting by a versatile command FI (fix parameter) with options like FI $\{t1-3\ 4\ 10\ 80-400\ t5\}$ (“exclude parameters belonging to transformation matrices T^1, T^2, T^3, T^5 and parameters Nos. 4, 10 and 80 to 400 from the fit”). Command FR (“free a parameter for fit”) is the opposite

Table 2
 Constants of the theory for grazing incidence time spectrum.

GLOBAL	<i>flag_Voigt</i>	Voigt/Gaussian profile
	<i>v_max</i>	max velocity in energy domain
	<i>i_T_max</i>	number of previous bunches
	<i>k_extension</i>	$2^{k_extension}$ times the number of channels for the Fourier transformation
	<i>jg, je, etc.</i>	nuclear constants
	<i>kGm/mm/s</i>	energy to velocity conversion
	<i>unit_thick</i>	unit of <i>thicklay</i>
	<i>unit_chi</i>	unit of <i>r_chilay</i> and <i>i_chilay</i>
LAYER	<i>n_repetition</i>	repetitions in the sandwich layer
SITE	$\pm Cnz, Cny$	n_z, n_y -fold symmetry axis, sign: time inversion

of FI and it removes the fixed flag on the parameter list and allows variation during fitting. Although the parameter space is presently restricted to a maximum of 32 free parameters at a time, much higher dimensional fits can be automatically made by FIXing and FREEing parameter subsets even by a single or recursively called command string.

Besides data input, parameter input/output files and the fit result output files, which contain the theoretical curves and errors and the χ^2 fit results, there are two further files to mention. The history file lists all commands given to the program and the error messages during session, which may be used later for error analysis. The session file stores the command buffers. It is especially useful for the RD (read) commands of the data sets and of the parameter files (the latter describing the structure of the model, the “theory”). The session file is typically used to start a session and read automatically all spectra and theories such that the last session is easily continued.

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